

Claims 1-32 are cancelled.

33. (new) An industrial robot, comprising:

a swivel having two coaxial, mutually rotatable members and having a plurality of means for transferring operating and/or controlling media between the rotatable members, wherein said means are flexible hoses or cables between the
5 rotatable members, wherein the flexible hoses or cables are elastically extensible;
means for attaching said swivel to a portion of the industrial robot.

34. (new) The industrial robot according to claim 33, wherein flexible
10 hoses or cables are spiral hoses or cables.

35. (new) The industrial robot according to claim 33, wherein the flexible hoses or cables are connected to the rotatable members by means of quick-couplings.

15 36. (new) The industrial robot according to claim 33, wherein a cylindrical housing for enclosing the flexible hoses or cables between the two members is provided.

37. (new) The industrial robot according to claim 33, wherein one of the
20 rotatable members is a lower connection ring and the other rotatable member is a cover, the cover being connected to a central shaft, in relation to which the lower connection ring is journalled.

38. (new) The industrial robot according to claim 37, wherein the cover
25 is connected to the central shaft by means of a quick-coupling.

39. (new) The industrial robot according to claim 37, wherein the lower connection ring and the cover are each provided with a plurality of through holes.

40. (new) The industrial robot according to claim 37, wherein the central
5 shaft is arranged on a base plate.

41. (new) The industrial robot according to claim 32, wherein the mutual rotation between the two rotatable members is limited to no more than one full revolution.

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42. (new) The industrial robot according to claim 37, wherein said flexible hoses or cables are connected generally axially to the central shaft when the rotatable members are in a non-rotated position.